

WEST Search History

DATE: Thursday, March 02, 2006

Hide?	Set Name	Query	Hit Count
		<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L31	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and L30	22
<input type="checkbox"/>	L30	(VR or virtual reality or VW or virtual world or virtual world or computer\$4 control) and L29	25
		(6268853 6292830 5358325 5844392 6304050 4578764 5239457 4475160 4843566 4890241 5268837 5353386 5559695 5579444 5802201 5825981 6115480 6697707 5182641 5331413 4905138 5341459 6445964 5696892 5715834 5381158 5659779 5760826 6064964 6618856 5790401 5950006 4590578 4831548 5177563 5355509 5577134 6052717 6215898 6215898 6567812 6157873 5805864 6044442 5559995 5588104 4826392 5602968 5963710 6439069).pn.	
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<input type="checkbox"/>	L27	gps receiver and transceiver and sensor and control and L26	11
<input type="checkbox"/>	L26	(VR or virtual reality or VW or virtual world or virtual world or computer\$4 control)and L25	313
<input type="checkbox"/>	L25	L17 and L24	3384
<input type="checkbox"/>	L24	(700/245 701/2 701/3 701/16 701/36 340/961 244/189).ccls.	4123
<input type="checkbox"/>	L23	control module and L20	5
<input type="checkbox"/>	L22	rfid and L20	6
<input type="checkbox"/>	L21	forklift and L20	5
<input type="checkbox"/>	L20	L17 and gps receiver and sensor and transceiver and (VR or virtual reality or VW or virtual world)	52
<input type="checkbox"/>	L19	gps receiver and L18	24
<input type="checkbox"/>	L18	data task and L17	1313
<input type="checkbox"/>	L17	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4)	7107952
<input type="checkbox"/>	L16	status and data and stask	1
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<input type="checkbox"/>	L11	status data and stask data (VW or virtual world or computer\$4 control)	0
<input type="checkbox"/>	L10	10/691971	1
<input type="checkbox"/>	L9	virtual and control and forklift and plant and robot and process control	19

<input type="checkbox"/>	L8	virtual and control and forklift and plant and robot and process and geospacial	0
<input type="checkbox"/>	L7	virtual and control and forklift and plant and robot and process control and geospacial	0
<input type="checkbox"/>	L6	virtual and control and foklift and plant and robot and process control and geospacial	0
<input type="checkbox"/>	L5	virtual and L4	98
<input type="checkbox"/>	L4	time reference and L3	355
<input type="checkbox"/>	L3	robot\$6 and L2	31436
<input type="checkbox"/>	L2	"second data stream" and time or period	2080765
<input type="checkbox"/>	L1	10/691971	1

END OF SEARCH HISTORY

Key: IEEE JNL = IEEE Journal or Magazine, IEE JNL = IEE Journal or Magazine, IEEE CNF = IEEE Conference, IEE CNF = IEE Conference, IEEE STD = IEEE Standard

1. **Knowledge sharing among multiple autonomous mobile robots through indirect communication using intelligent data carriers**
 Fujii, T.; Asama, H.; Fujita, T.; Asakawa, Y.; Kaetsu, H.; Matsumoto, A.; Endo, I.; Intelligent Robots and Systems '96, IROS 96, Proceedings of the 1996 IEEE/RSJ International Conference on
 Volume 3, 4-8 Nov. 1996 Page(s):1466 - 1471 vol.3
 IEEE CNF
2. **Mutual transportation of cooperative mobile robots using forklift mechanisms**
 Asama, H.; Sato, M.; Goto, N.; Kaetsu, H.; Matsumoto, A.; Endo, I.; Robotics and Automation, 1996. Proceedings., 1996 IEEE International Conference on
 Volume 2, 22-28 April 1996 Page(s):1754 - 1759 vol.2
 IEEE CNF
3. **Environment manipulation planner for humanoid robots using task graph that generates action sequence**
 Okada, K.; Haneda, A.; Nakai, H.; Inaba, M.; Inoue, H.; Intelligent Robots and Systems, 2004. (IROS 2004). Proceedings. 2004 IEEE/RSJ International Conference on
 Volume 2, 28 Sept.-2 Oct. 2004 Page(s):1174 - 1179 vol.2
 IEEE CNF
4. **Decentralized control of cooperating mobile manipulators**
 Sugar, T.; Kumar, V.; Robotics and Automation, 1998. Proceedings. 1998 IEEE International Conference on
 Volume 4, 16-20 May 1998 Page(s):2916 - 2921 vol.4
 IEEE CNF
5. **Industrial exploitation of computer vision in logistic automation: autonomous control of an intelligent forklift truck**
 Garibotto, G.; Masciangelo, S.; Bassino, P.; Coelho, C.; Pavan, A.; Marson, M.; Robotics and Automation, 1998. Proceedings. 1998 IEEE International Conference on
 Volume 2, 16-20 May 1998 Page(s):1459 - 1464 vol.2
 IEEE CNF
6. **Computer vision control of an intelligent forklift truck**
 Garibotto, G.; Masciangelo, S.; Bassino, P.; Ilic, M.; Intelligent Transportation System, 1997. ITSC 97. IEEE Conference on
 9-12 Nov. 1997 Page(s):589 - 594
 IEEE CNF
7. **A camera space control system for an automated forklift**
 Miller, R.K.; Stewart, D.G.; Brockman, W.H.; Skaar, S.B.; Robotics and Automation, IEEE Transactions on
 Volume 10, Issue 5, Oct. 1994 Page(s):710 - 716
 IEEE JNL